the extrema subject to two constraints is on page 11 in the link above

## 5 Extrema subject to two constraints

Here is Theorem 1 with m = 2.

**Theorem 3** Suppose that n > 2. If  $X_0$  is a local extreme point of f subject to  $g_1(X) = g_2(X) = 0$  and

$$\frac{\frac{\partial g_1(\mathbf{X}_0)}{\partial x_r}}{\frac{\partial g_2(\mathbf{X}_0)}{\partial x_s}} \stackrel{\partial g_1(\mathbf{X}_0)}{\frac{\partial g_2(\mathbf{X}_0)}{\partial x_r}} \neq 0$$
(19)

for some r and s in  $\{1, 2, ..., n\}$ , then there are constants  $\lambda$  and  $\mu$  such that

$$\frac{\partial f(\mathbf{X}_0)}{\partial x_i} - \lambda \frac{\partial g_1(\mathbf{X}_0)}{\partial x_i} - \mu \frac{\partial g_2(\mathbf{X}_0)}{\partial x_i} = 0,$$
(20)

 $1 \leq i \leq n$ .

**Proof** For notational convenience, let r = 1 and s = 2. Denote

 $U = (x_3, x_4, \dots x_n)$  and  $U_0 = (x_{30}, x_{30}, \dots x_{n0})$ .

Since

$$\frac{\frac{\partial g_1(\mathbf{X}_0)}{\partial x_1}}{\frac{\partial g_2(\mathbf{X}_0)}{\partial x_1}} = \frac{\frac{\partial g_2(\mathbf{X}_0)}{\partial x_2}}{\frac{\partial g_2(\mathbf{X}_0)}{\partial x_1}} \neq 0, \qquad (21)$$

the Implicit Function Theorem (Theorem 6.4.1, p. 420) implies that there are unique continuously differentiable functions

$$h_1 = h_1(x_3, x_4, \dots, x_n)$$
 and  $h_2 = h_1(x_3, x_4, \dots, x_n)$ ,  
defined on a neighborhood  $N \subset \mathbb{R}^{n-2}$  of U<sub>0</sub>, such that  $(h_1(U), h_2(U), U) \in D$  for all  
 $U \in N, h_1(U_0) = x_{10}, h_2(U_0) = x_{20}$ , and

I don't get how they can take the derivative of  $g_1$  and  $g_2$  with respect to  $x_1$  and  $x_2$  when they are defined as

$$h_1 = h_1(x_3, x_4, \dots, x_n) = x_1$$
 and  $h_2 = h_2(x_3, x_4, \dots, x_n) = x_2$ 

I need a mathematical justification for how this can be written simply as (21) when  $x_1$  and  $x_2$  are defined as functions from other variables:  $x_3, x_4, ..., x_n$ 

Is it by using the chain rule or something else? Please og through the detailed steps for how this can be a normal quadratic matrix as defined in the implicit function theorem and by that showing why this is an appliable form of the implicit function theorem nonsingular matrix in (21): The function G has image in  $\mathbb{R}^2$ , so we call the two components  $h_1$  and  $h_2$ , that is,  $G(Y) = (h_1(Y), h_2(Y))$  where  $h_1, h_2 : \mathbb{R}^{n-2} \to \mathbb{R}$ . For us  $Y = (x_3, \ldots, x_n)$ , therefore both functions  $h_1$  and  $h_2$  depend on  $(x_3, \ldots, x_n)$  and we write that by saying  $h_1 = h_1(x_3, \ldots, x_n)$  and  $h_2 = h_2(x_3, \ldots, x_n)$  (there is a typo there in the book, certainly it is not necessarily true that  $h_2 = h_1$ ). The two functions  $h_1, h_2$  are defined on the neighborhood N of  $Y_0$  in  $\mathbb{R}^{n-2}$ . Now, from (3), for all  $\mathbf{Y} \in N$ ,  $(G(\mathbf{Y}), \mathbf{Y}) = (h_1(\mathbf{Y}), h_2(\mathbf{Y}), \mathbf{Y}) \in M$ . As  $M \subseteq D$  we have  $(h_1(\mathbf{Y}), h_2(\mathbf{Y}), \mathbf{Y}) \in D$ .

Theorem 6.4.1 (The Implicit Function Theorem) Suppose that  $F : \mathbb{R}^{n+m} \to \mathbb{R}^m$  is continuously differentiable on an open set S of  $\mathbb{R}^{n+m}$  containing  $(X_0, U_0)$ . Let  $F(X_0, U_0) = 0$ , and suppose that  $F_U(X_0, U_0)$  is nonsingular. Then there is a neighborhood M of  $(X_0, U_0)$ , contained in S, on which  $F_U(X, U)$  is nonsingular and a neighborhood N of  $X_0$  in  $\mathbb{R}^n$  on which a unique continuously differentiable transformation  $G : \mathbb{R}^n \to \mathbb{R}^m$  is defined, such that  $G(X_0) = U_0$  and

Search for the theorem in this link if you want to see more from the implicit function theorem. It is on page 420

http://ramanujan.math.trinity.edu/wtrench/texts/TRENCH\_REAL\_ANALYSIS.PDF