Calculate the linear state space matrices A, B, C, and D for a system that is 2 described by the following state equations, for deviations from $\mathbf{u}_{op} = \begin{bmatrix} -1, & -1 \end{bmatrix}^T$, $\mathbf{x}_{op} = \begin{bmatrix} 1, & 1, & 0 \end{bmatrix}^T$, and $\mathbf{y}_{op} = \begin{bmatrix} 0 \end{bmatrix}$.

$$\dot{x}_1 = x_2^2 - \cos x_3$$

$$\dot{x}_2 = (1 + x_1 x_2) x_3$$

$$\dot{x}_3 = x_1 (u_1 + x_2)$$

$$y = (x_1 - 1) u_2$$

[6 pts]

[4 pts]

[23 pts]

[7 pts]

A linear system is described by its transfer function $T(s) = \frac{s-1}{s^2+6s+5}$. 3

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- Derive the time-domain expression for the unit step response of this system. 3.1 5 pts
- 3.2 Sketch the unit step response of this system over 3 times the longer of the two time constants.
- A linear system is described by its transfer function $T(s) = \frac{18+59.1s-3s^2}{(s^2+0.3s+9)(20+s)}$. Draw the Bode magnitude and phase angle plots of $T(j\omega)$ on the attached EdS 4.1 graph paper for $0.03 \le \omega \le 30$.
- Transfer the frequency response from the Bode plot to the adjacent logarithmic 4.2 complex plane. Mark $\omega = 0.1$, 0.4, 3, and 10 on the frequency response.