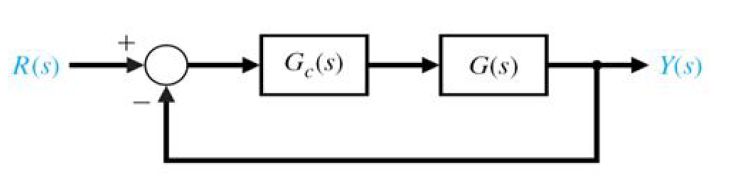
**5.**



In the figure above, if

mathml 
equation and mathml equation

find the gain (K) of the compensator so that overall closed-loop response to a unit step input has a maximum overshoot of mathml equation, and a 2% settling time of 0.1 sec.

**7.** For a unity feedback system, the plant or process is:

mathml 
equation

Find the steady state error when the input is:

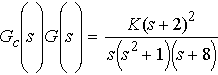
mathml equation

**8.** A system with unity feedback has the following process transfer function:

mathml equation

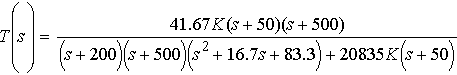
Determine the type and the steady-state error for a step input.

**11.** A single-loop negative feedback system has a loop transfer function:



Determine the range of the gain K for which the system is stable using Routh-Hurwitz.

**13.** The closed-loop transfer of a given system is given by the following:



Determine the steady-state error when the K=10 for a step-input.