

7. Gaussian vectors, spaces, measures, processes

7.1 Gaussian Random Variables

$$d=1 \\ X \text{ is } \mathcal{N}(0,1) \Leftrightarrow f_X(x) = \frac{1}{\sqrt{2\pi}} \exp\left(-\frac{x^2}{2}\right)$$

↓
density

$$\mathbb{E}[e^{zX}] = e^{z^2/2} \quad \forall z \in \mathbb{R} \quad \Bigg| \Rightarrow \quad \mathbb{E}[e^{zX}] = e^{z^2/2} \quad \forall z \in \mathbb{C}$$

↓
 $\mathbb{E}[e^{zX}]$ is analytic on \mathbb{C}

$$z = i\xi, \quad \xi \in \mathbb{R} \\ \mathbb{E}[e^{i\xi X}] = e^{-\xi^2/2}$$

From the development

$$\mathbb{E}[e^{i\xi X}] = 1 + i\xi \mathbb{E}[X] + \dots + \frac{(i\xi)^n \mathbb{E}[X^n]}{n!} + o(|\xi|^{n+1})$$

which is valid if $\forall p > 0, \mathbb{E}[|X|^p] < \infty$

we compute

$$\mathbb{E}[X] = 0 \quad \mathbb{E}[X^2] = 1 \quad \mathbb{E}[X^{2n}] = \frac{(2n)!}{2^n n!}$$

Def 7.1

We say that a real rand. var Y has a Gaussian $\mathcal{N}(m, \sigma^2)$ law iff one of the following equivalent properties is ^{one} satisfied

(i) $Y = \sigma X + m$ where X is $\mathcal{N}(0, 1)$

(ii) $f_Y(y) = \frac{1}{\sigma \sqrt{2\pi}} \exp \left[-\frac{(y-m)^2}{2\sigma^2} \right]$

(iii) $E[e^{i\xi Y}] = \exp \left[im\xi - \frac{\sigma^2}{2} \xi^2 \right]$

we have then $E[Y] = m$ $\text{Var}[Y] = \sigma^2$

Rk Assume that Y is $\mathcal{N}(m, \sigma^2)$ & Y' is $\mathcal{N}(m', \sigma'^2)$ and Y & Y' are indep.

Then $Y + Y'$ is $\mathcal{N}(m+m', \sigma^2 + \sigma'^2)$

Proposition 2

Let (X_n) be a sequ. of Gauss. rand. var
such that X_n is $\mathcal{N}(m_n, \sigma_n^2)$

Assume that $X_n \xrightarrow[n \rightarrow \infty]{law} X$

Then $\iff X$ is $\mathcal{N}(m, \sigma^2)$

$$m_n \xrightarrow[n \rightarrow \infty]{} m \qquad \sigma^2 = \lim_{n \rightarrow \infty} \sigma_n^2$$

$\exists \iff \text{If } X_n \xrightarrow[n \rightarrow \infty]{prob.} X \text{ then}$

$$\forall p < \infty \quad X_n \xrightarrow[n \rightarrow \infty]{L^p(\Omega)} X \quad (\iff E[|X - X_n|^p] \xrightarrow[n \rightarrow \infty]{} 0)$$

7.2 Gaussian Vectors

E : Euclidean space of dim d
 (E is isomorphic to \mathbb{R}^d)

$\langle u, v \rangle$: The scalar product of E

Def 7.3

$X: \Omega \rightarrow E$ is a Gaussian vector

iif $\forall u \in E$, $\langle u, X \rangle$ is a Gaussian random variable

Ex: If $E = \mathbb{R}^d$ & X_1, \dots, X_d are indep Gauss. rand var.
 then $X = (X_1, \dots, X_d)$ is a Gauss. vector

Def 7.4

A mapping $B: E \times E \rightarrow \mathbb{R}$

is called a symmetric bilinear form on E iff

$$\forall \lambda, u, v, w \in \mathbb{R} \times E \times E \times E$$

$$B(\lambda u + w, v) = \lambda B(u, v) + B(w, v)$$

$$B(u, v) = B(v, u)$$

Def 7.5

$Q: E \rightarrow \mathbb{R}$

is a positive quadratic form on E iff

\exists a symmetric bilinear form on E such that

$$Q[u] = B[u, u]$$

and $\forall u \in E, Q[u] \geq 0$

$$Rk: B[u, v] = \frac{1}{2} [Q[u+v] - Q[u] - Q[v]]$$

Proposition 7.6

If X is a Gaussian vector with values in E there exists $m_x \in E$ and a positive quadratic form Q_x on E such that $\forall u \in E$

$$\mathbb{E}[\langle u, X \rangle] = \langle u, m_x \rangle$$

$$\text{Var}[\langle u, X \rangle] = Q_x[u]$$

$$\mathbb{E}[\exp(i \langle u, X \rangle)] = \exp[i \langle u, m_x \rangle - \frac{1}{2} Q_x[u]]$$

proof

Let (e_1, e_2, \dots, e_d) be an orthonormal basis of E and $X = \sum_{j=1}^d X_j e_j$ the decomposition of X in this basis.

The rand. var. X_j are Gaussian

It is easy to check that $m_x = \sum_{j=1}^d \mathbb{E}[X_j] e_j$ ($= \mathbb{E}[X]$)
↓
notation

and if $u = \sum_{j=1}^d u_j e_j$ $Q_x[u] = \sum_{j,k=1}^d u_j u_k \text{Cov}(X_j, X_k)$

the Fourier transform follows from the fact that

$$\langle u, X \rangle \text{ is } \mathcal{N}[\langle u, m_x \rangle, Q_x[u]]$$

Proposition 7.7

Under the previous assumptions, the random variables X_1, \dots, X_d are indep. iff the covariance matrix $(\text{Cov}(X_j, X_k))$ is diagonal, or iff the quadratic form Q_X is diagonal in the basis (e_1, \dots, e_d)

$$\left(\begin{array}{l} Q_X[v] = B[v, v] \\ B[e_i, e_j] = \lambda_j \delta_{ij} \end{array} \right)$$

proof:

X_1, \dots, X_d indep $\Rightarrow (\text{Cov}(X_j, X_k))_{j,k=1, \dots, d}$ diagonal
trivial

If $(\text{Cov}(X_j, X_k))_{j,k}$ is diagonal then

$$Q_X[v] = \sum_{j=1}^d \lambda_j v_j^2 \quad \text{where } \lambda_j = \text{Var}[X_j]$$

thus

$$\begin{aligned} E\left[\exp\left(i \sum_{j=1}^d v_j X_j\right)\right] &= \prod_{j=1}^d \exp\left[i v_j E[X_j] - \frac{1}{2} \lambda_j v_j^2\right] \\ &= \prod_{j=1}^d E\left[\exp(i v_j X_j)\right] \end{aligned}$$

$\Rightarrow X_1, \dots, X_d$ are indep.

Def γ is a symmetric positive endomorphism on E

iif γ is a linear function from E onto E

such that $\forall u, v \in E$

$$(u, \gamma[v]) = (\gamma[u], v)$$

$$(u, \gamma[u]) \geq 0$$

Rk: Q_x is a quadratic form \Leftrightarrow

\exists a symmetric positive endomorphism associated to $Q_x /$

$$\forall u \in E, Q_x[u] = \langle u, \gamma_x[u] \rangle$$

The matrix of γ_x in the basis (e_1, \dots, e_d)

is $(\text{Cov}(X_j, X_k))$ but the definition of γ_x doesn't

depend on the basis

$$\langle v, \gamma_x[u] \rangle = \frac{1}{4} [Q_x[u+v] - Q_x[u-v]]$$

\rightarrow From now on, to simplify the presentation

we will restrict ourselves to centered Gauss vect.,

i.e. such that $m_x = 0$

Thm 7.8

1) If δ is a symmetric positive endomorphism on E , then there exists a centered Gaussian vector X such that $\delta_X = \delta$

2) Let X be a centered Gaussian vector

$(\varepsilon_1, \dots, \varepsilon_d)$ a basis of E diagonalizing δ_X

$$\delta_X \varepsilon_j = \lambda_j \varepsilon_j \quad \text{with} \quad \lambda_1 \geq \lambda_2 \geq \dots \geq \lambda_r > 0 = \lambda_{r+1} = \dots = \lambda_d$$

(r is the rank of δ_X)

$$\text{Then } X = \sum_{j=1}^r \gamma_j \varepsilon_j$$

where the random variables γ_j are indep. centered Gaussian rand. var. of variance λ_j

If \mathbb{P}_X stands for the law of X , the

topological support of \mathbb{P}_X is $\text{span}(\varepsilon_1, \dots, \varepsilon_r)$

Ex

Let $X = (X_1, X_2, X_3)$ be a centered Gaussian vector with covariance matrix

$$K = \begin{pmatrix} 3 & 0 & 2 \\ 0 & 2 & 1 \\ 2 & 1 & 2 \end{pmatrix}$$

- a) What is the law of $X_2 + X_3$?
- b) Are $X_2 + X_3$ & X_1 independent?
- c) Are $X_2 + X_3$ & $X_2 - X_3$ independent?
- d) What is $E[X_1 | X_2, X_3]$?
- e) What is the conditional law of X_1 conditioned on (X_2, X_3) ?

Sol

$$\begin{aligned} \text{a) } V[X_2 + X_3] &= V[X_2] + V[X_3] + 2 \text{Cov}[X_2, X_3] \\ &= \underset{(0,1,1)}{K} \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix} = 2 + 2 + 2 = 6 \end{aligned}$$

$X_2 + X_3$ is $\mathcal{N}(0, 6)$

$$\begin{aligned} \underline{b)} \quad \text{Cov}(X_1, X_2 + X_3) &= (1 \ 0 \ 0) K \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix} \\ &= \text{Cov}(X_1, X_2) + \text{Cov}(X_1, X_3) \\ &= 0 + 2 \neq 0 \end{aligned}$$

\Rightarrow They are not independent

$$\begin{aligned} \underline{c)} \quad \text{Cov}(X_2 + X_3, X_2 - X_3) &= \text{Var}[X_2] - \text{Var}[X_3] \\ &= 2 - 2 \\ &= 0 \end{aligned}$$

\Rightarrow They are indep.

$$\underline{d)} \quad \mathbb{E}[X_1 | X_2, X_3] = aX_2 + bX_3$$

$$\text{Cov}(X_1 - aX_2 - bX_3, X_2) = 0$$

$$\text{Cov}(X_1 - aX_2 - bX_3, X_3) = 0$$

$$\left. \begin{aligned} -2a - b &= 0 \\ 2 - a - b &= 0 \end{aligned} \right\}$$

$$\mathbb{E}[X_1 | X_2, X_3] = -\frac{2}{3}X_2 + \frac{4}{3}X_3$$

$$\underline{e)} \quad \text{Law of } (X_1 | X_2, X_3) = \mathcal{N}(\mathbb{E}[X_1 | X_2, X_3], \sigma^2)$$

$$\sigma^2 = \text{Var}[X_1 - (-\frac{2}{3}X_2 + \frac{4}{3}X_3)]$$

$$= \frac{1}{3}$$

$$\text{Law}(X_1 | X_2, X_3) = \mathcal{N}\left(-\frac{2}{3}X_2 + \frac{4}{3}X_3, \frac{1}{3}\right)$$

7.2 Gaussian spaces and processes

Def 7.9

A (centered) Gaussian space is a closed subspace of $L^2(\Omega, \mathcal{U}, \mathbb{P})$ whose elements are centered Gaussian random variables.

Ex: If (X_1, \dots, X_d) is a centered Gauss. vector on \mathbb{R}^d , $\text{span}\{X_1, \dots, X_d\}$ is a Gaussian space

Let T be an arbitrary set

Def 7.10

A family $\{X_t, t \in T\}$ is a (centered)

Gaussian process iff $\forall n \in \mathbb{N}, \forall t_1, \dots, t_n \in T$

$\forall \lambda_1, \dots, \lambda_n \in \mathbb{R}$

$\lambda_1 X_{t_1} + \dots + \lambda_n X_{t_n}$

is a centered Gaussian random variable

Thm 7.11

Let H be a Gaussian space and let $(H_i, i \in I)$ be a family of closed sub-vector spaces of H .

Then the sub-spaces $H_i, i \in I$ are orthogonal in \mathbb{L}^2 ($\forall X_i \in H_i, X_j \in H_j, E[X_i X_j] = 0$)

iif the σ -algebra $\mathcal{G}(H_i), i \in I$ are indep.

($\mathcal{G}(H_i)$: σ -algebra generated by elements of H_i)
rand. var.

Rk It is important that the spaces H_i are contained in the same Gauss. space

$$\text{ex: } X_1 = X \quad X_2 = \varepsilon X \quad \varepsilon \text{ indep of } X$$

$$IP[\varepsilon = 1] = IP[\varepsilon = -1] = \frac{1}{2}$$

$$E[X_1 X_2] = E[\varepsilon] E[X^2] = 0$$

but X_1, X_2 are not indep (see $X_1 + X_2$)

Corollary 7.12

Let H be a Gaussian space and K a closed sub-vector space of H

Write p_K the orthogonal projection on K

$$\begin{aligned}
 p_K: H &\longrightarrow K \\
 X &\longrightarrow p_K(X) = \underset{z \in K}{\operatorname{argmin}} \mathbb{E}[|z - X|^2] \\
 &= \left\{ z \in K \text{ minimizing } \mathbb{E}[|z - X|^2] \right\}
 \end{aligned}$$

Let $X \in H$, we have

$$(i) \quad \mathbb{E}[X | \mathcal{G}(K)] = p_K(X)$$

$$(ii) \quad \text{Let } \sigma^2 = \mathbb{E}[(X - p_K(X))^2] \quad \text{then } \forall \Gamma \in \mathcal{B}(\mathbb{R})$$

$$\mathbb{P}[X \in \Gamma | \mathcal{G}(K)] = \frac{1}{\sigma \sqrt{2\pi}} \int_{\Gamma} dy \exp\left(-\frac{(y - \underset{\substack{\text{random } \in K \\ \downarrow \\ p_K(X)}}{p_K(X)}}{2\sigma^2}\right)$$

Rk In general

$$\mathbb{E}[X | \mathcal{G}(K)] = P_{L^2(\Omega, \mathcal{G}(K), \mathbb{P})}(X)$$

$$\text{here} = P_K(X)$$

K : much smaller than $L^2(\Omega, \mathcal{G}(K), \mathbb{P})$

Ex Let $X = (X_1, X_2, X_3)$ be a Gaussian vector. What is the best approximation of X_3 knowing X_1, X_2 ?

Sol: In general $\mathbb{E}[X_3 | X_1, X_2] = f(X_1, X_2)$

From the previous thm we know that

$$\mathbb{E}[X_3 | X_1, X_2] = \lambda_1 X_1 + \lambda_2 X_2$$

where λ_1, λ_2 are determined by the fact that

$X_3 - (\lambda_1 X_1 + \lambda_2 X_2)$ is \perp to $\text{span}(X_1, X_2)$
orthogonal